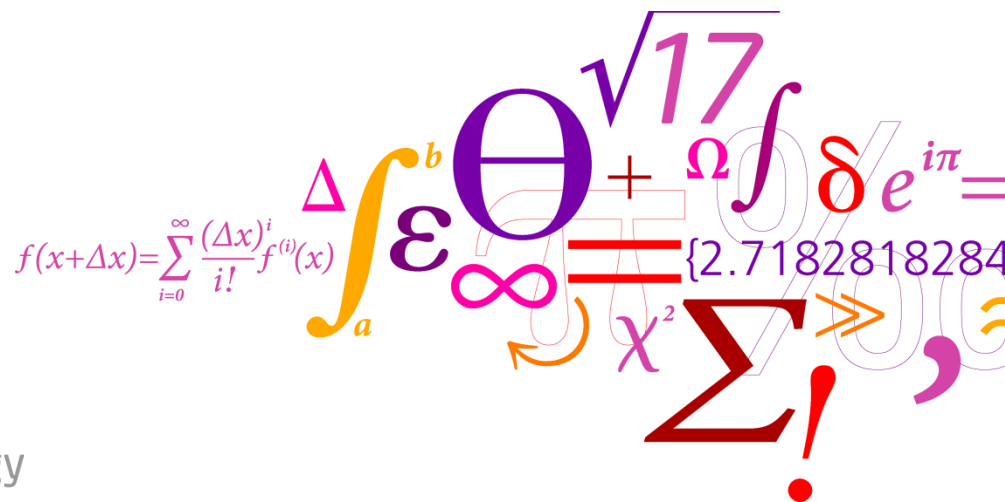


# Coupling the Navier Stokes actuator line model with the aeroelastic solver HAWC2 – work in progress

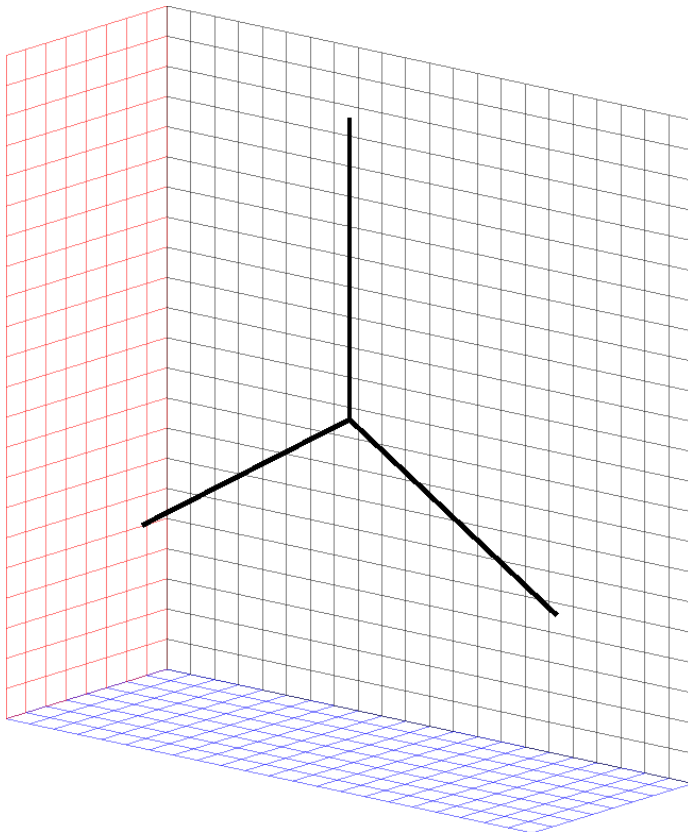
Niels Trolborg and Joachim Heinz

Wind Energy Department, DTU Wind Energy, DK-4000 Roskilde, Denmark



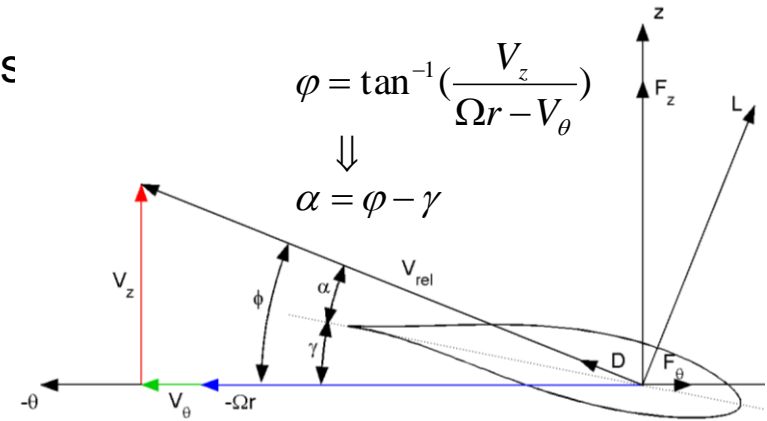
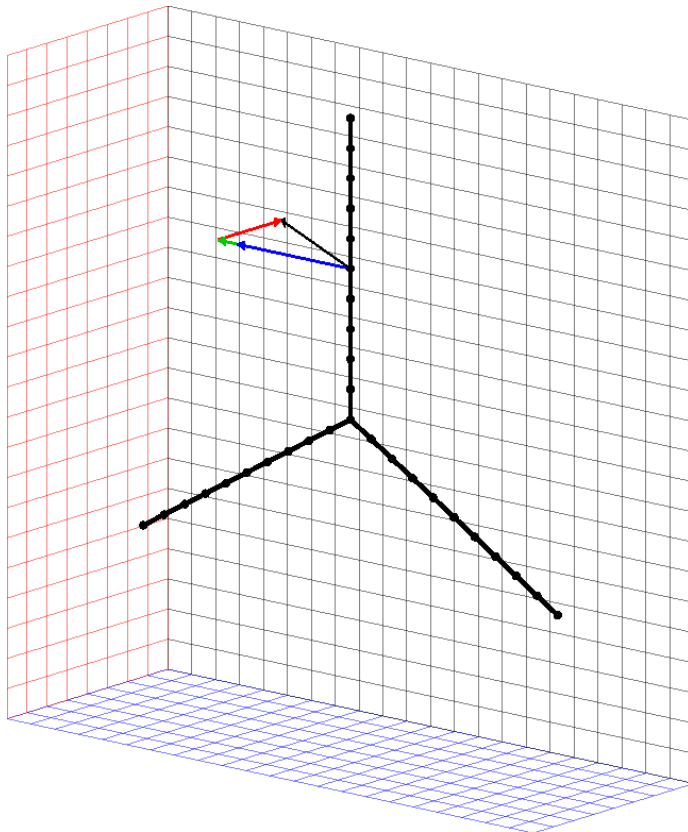
# Actuator Line/Navier-Stokes simulations

- Blades represented as lines
- Flow field determined from 3D N-S simulations

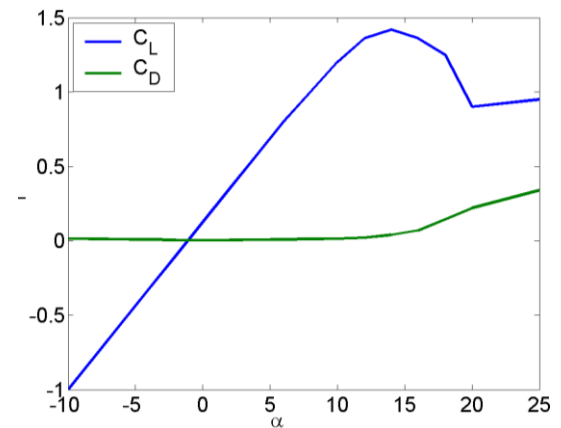


# Actuator Line/Navier-Stokes simulations

- Blades represented as lines
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- Aerodynamic forces at each blade section determined from 2D airfoil data

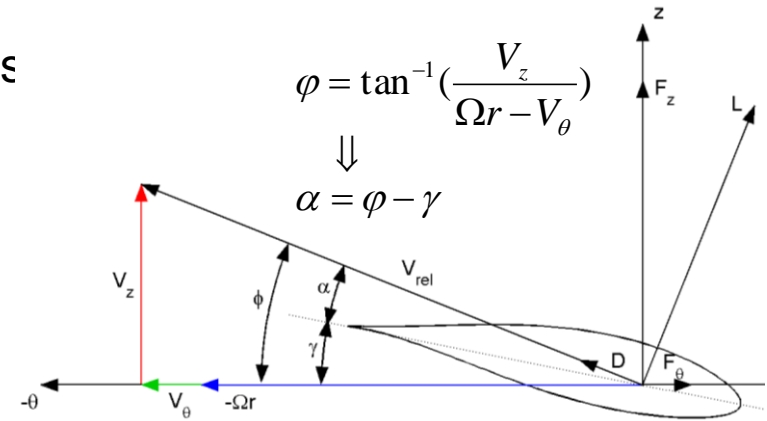
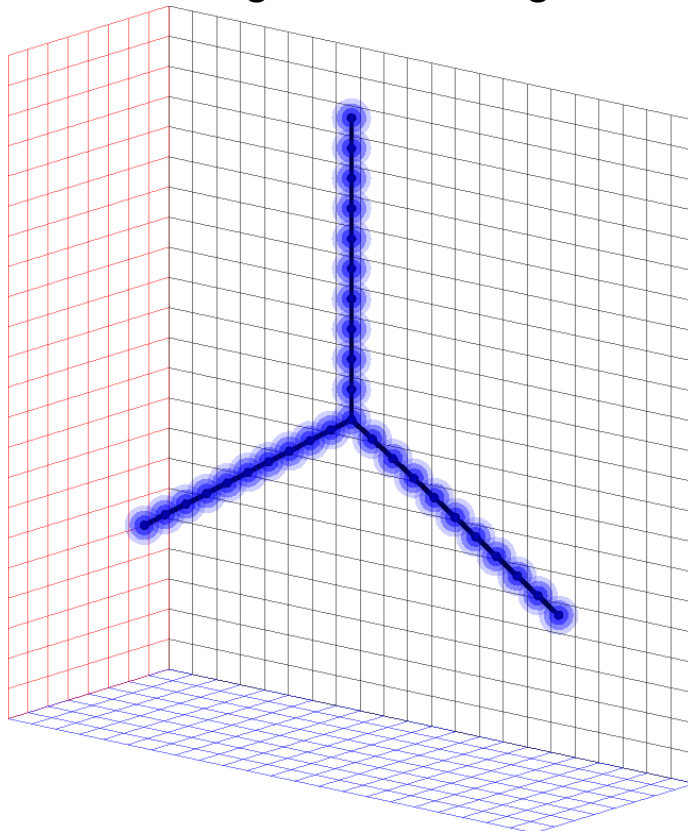


$$\mathbf{f} = \begin{pmatrix} L \\ D \end{pmatrix} = \frac{1}{2} \rho V_{rel}^2 c \begin{pmatrix} C_L(\alpha) \mathbf{e}_L \\ C_D(\alpha) \mathbf{e}_D \end{pmatrix}$$

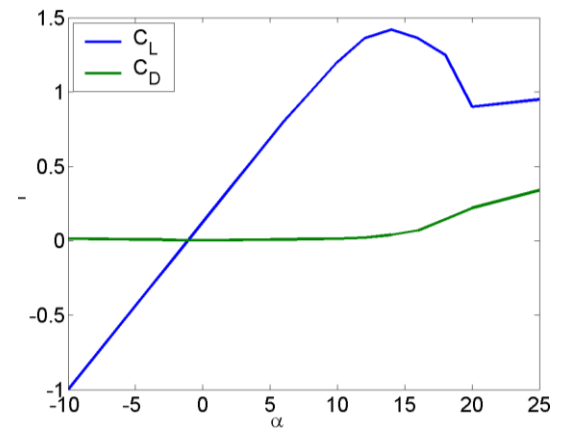


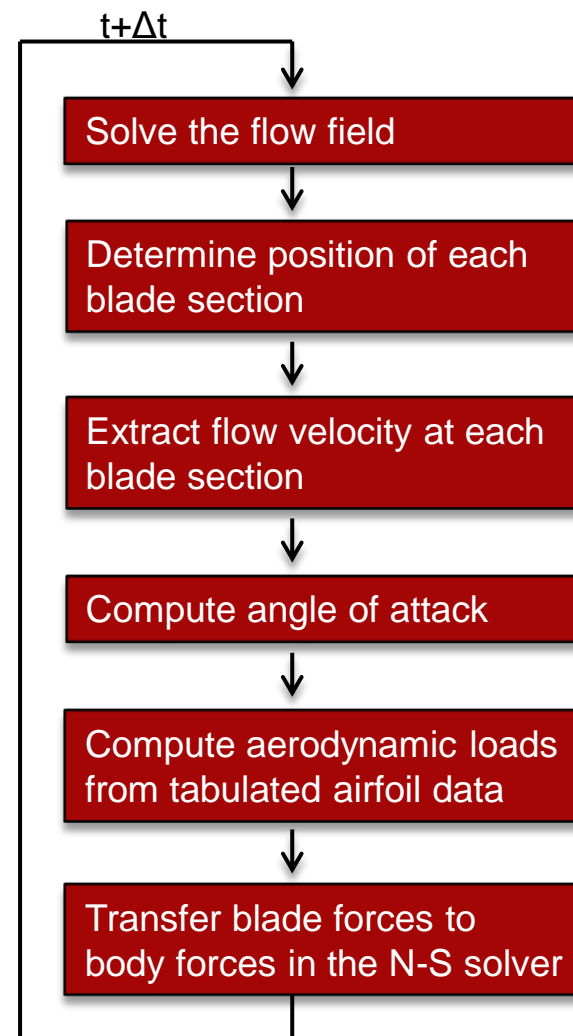
# Actuator Line/Navier-Stokes simulations

- Blades represented as lines
- Flow field determined from 3D N-S simulations
- Aerodynamic forces at each blade section determined from 2D airfoil data
- Blade forces transferred to N-S solver using Gaussian smearing to avoid singular behaviour

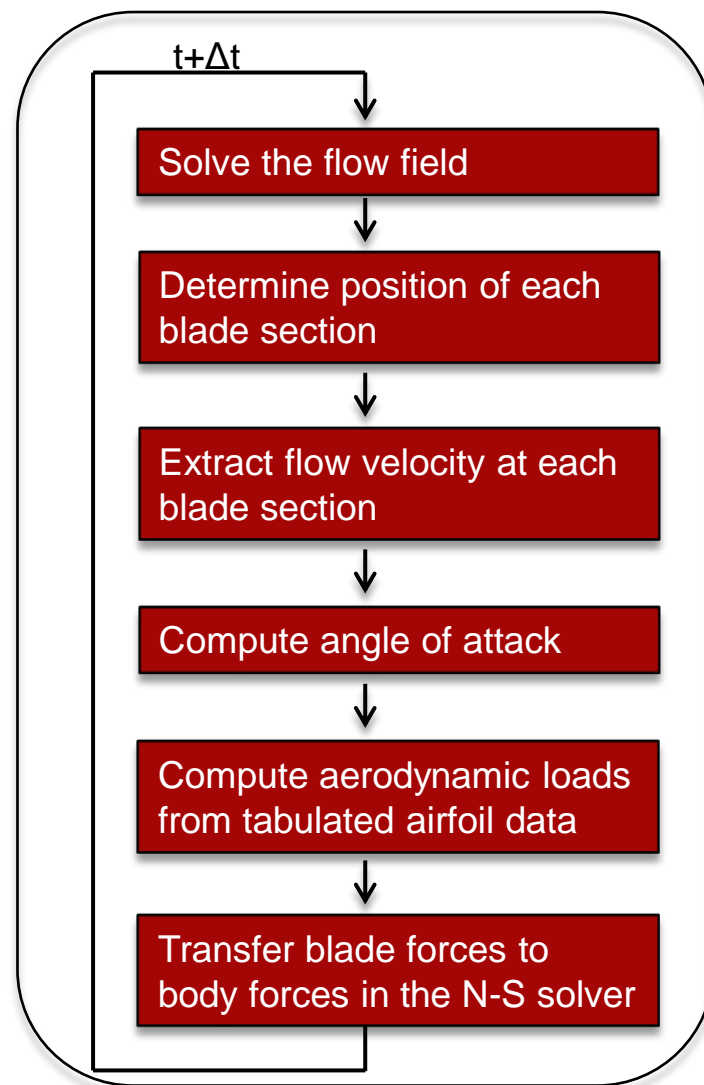


$$\mathbf{f} = \begin{pmatrix} L \\ D \end{pmatrix} = \frac{1}{2} \rho V_{rel}^2 c \begin{pmatrix} C_L(\alpha) \mathbf{e}_L \\ C_D(\alpha) \mathbf{e}_D \end{pmatrix}$$

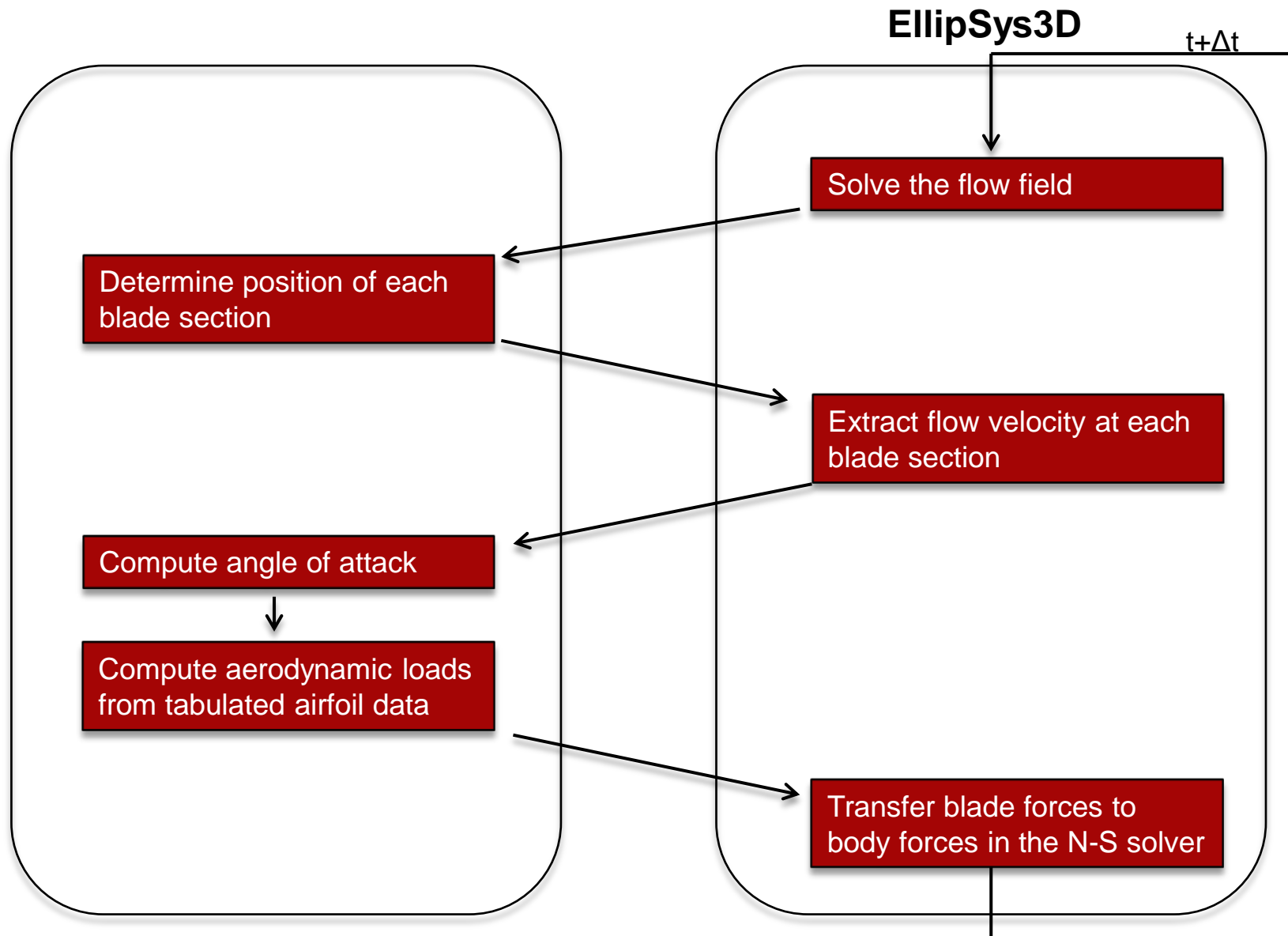




## EllipSys3D



# Actuator Line/Navier-Stokes simulations

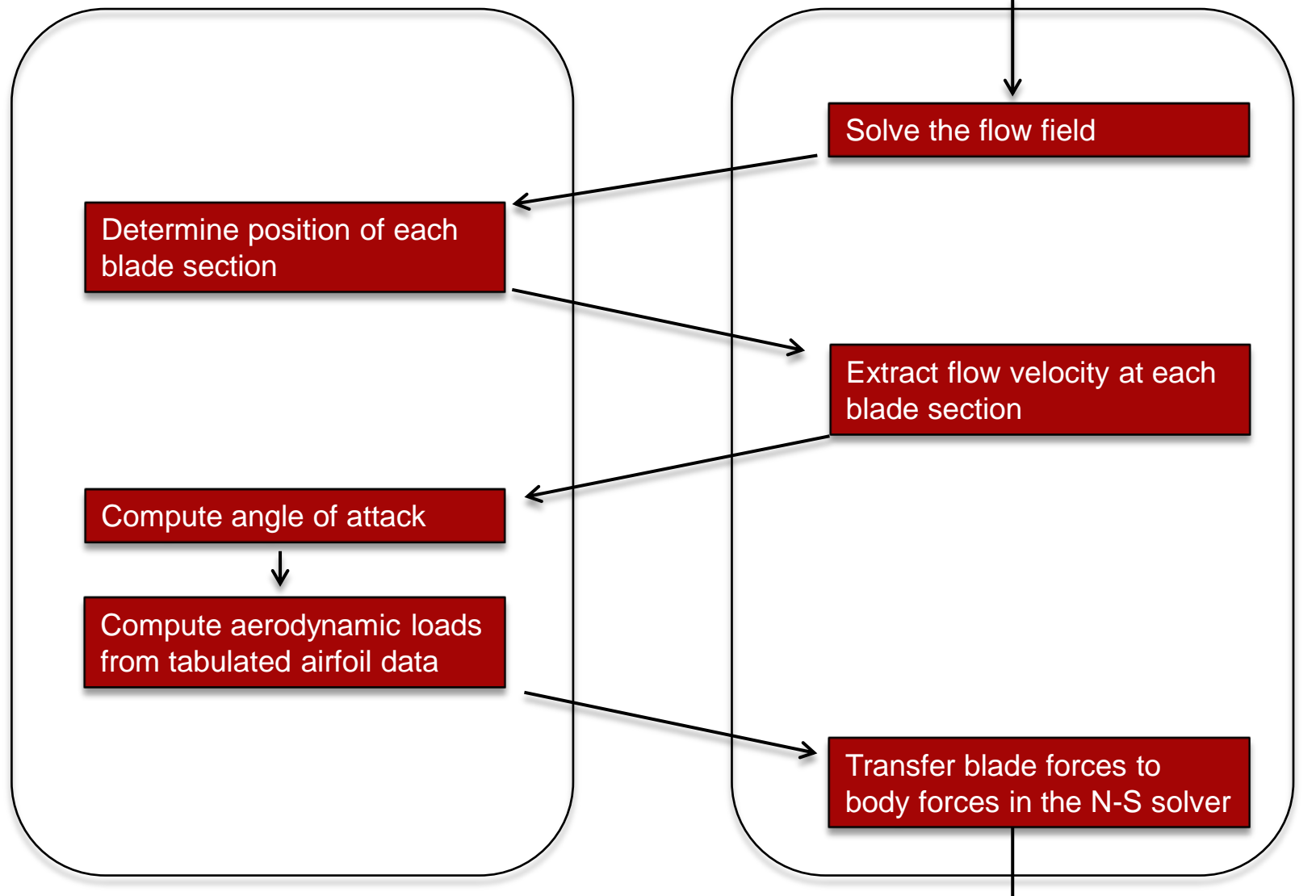


# HAWC2/Actuator Line/Navier-Stokes simulations

## HAWC2

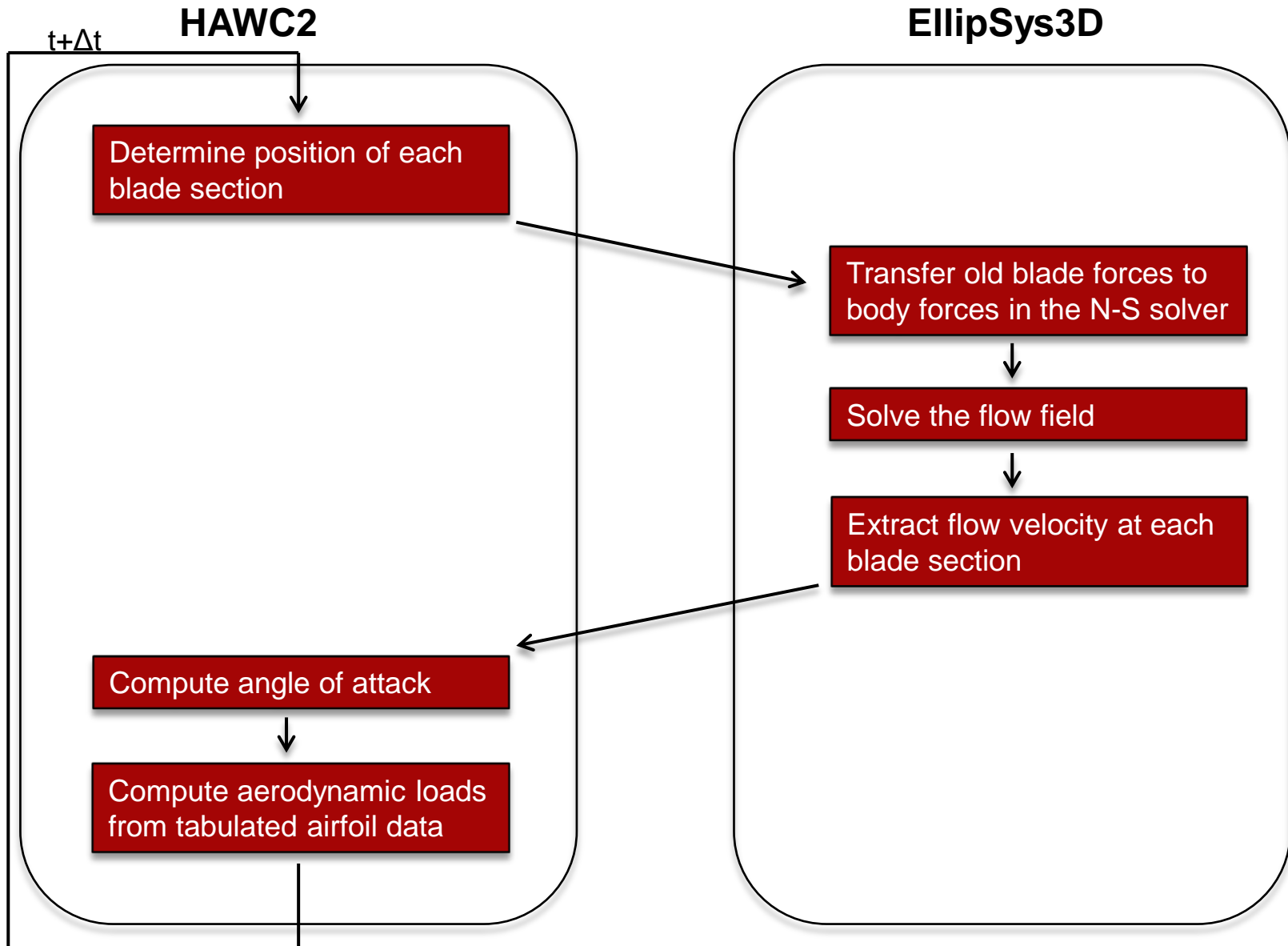
## EllipSys3D

$t + \Delta t$





# HAWC2/Actuator Line/Navier-Stokes simulations



# Generic coupling framework

## Step 1:

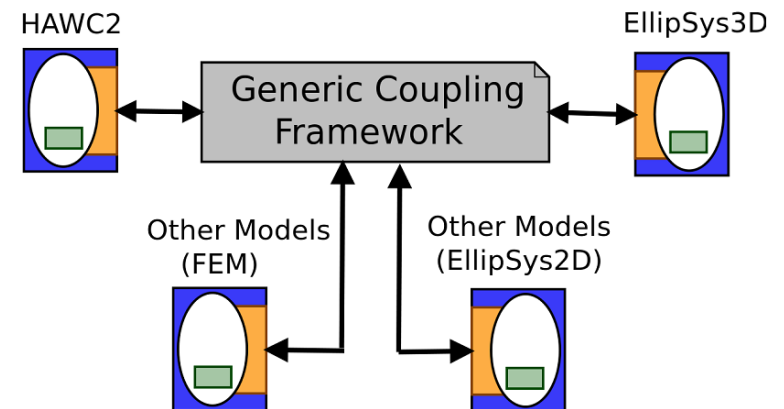
- Wrap the programs participating in the coupling

## Step 2:

- Import the wrapped programs into python

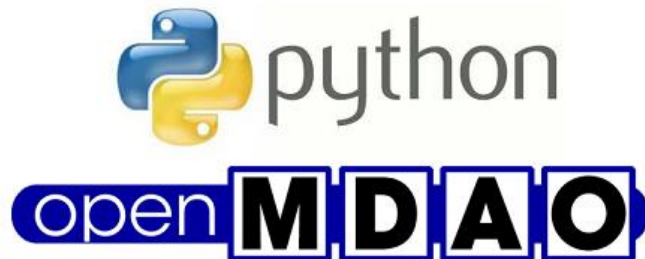
## Step 3:

- Python orchestrates the execution of the programs and organizes the input/output handling via the common script



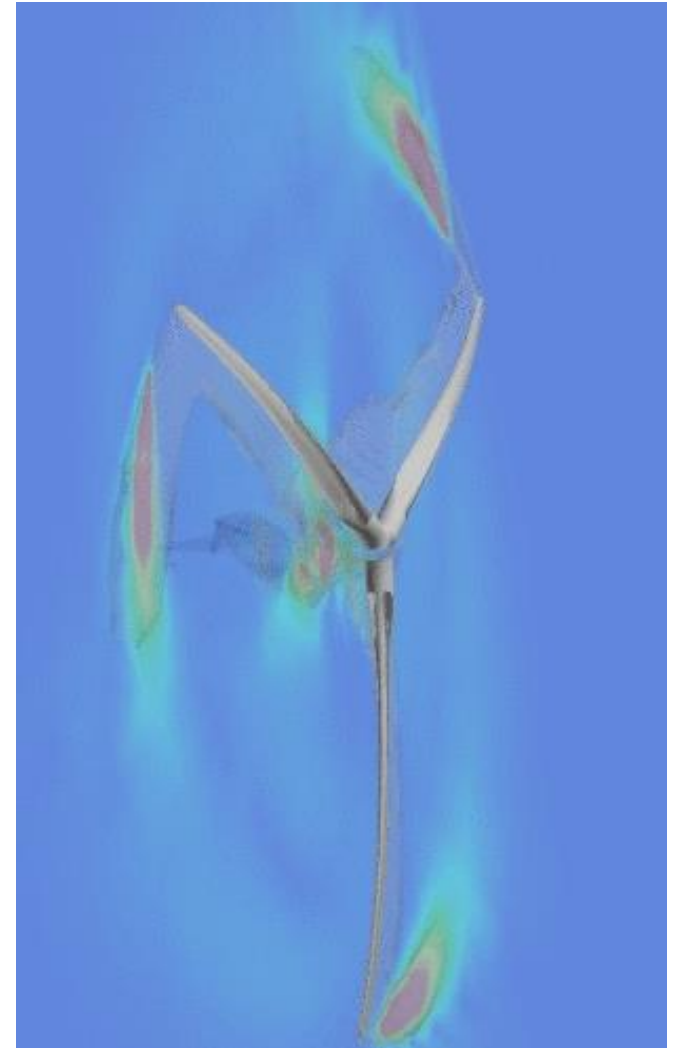
# Generic coupling framework

- OpenMDAO (Multidisciplinary Design Analysis and Optimization)
  - A framework for executing and connecting different types of codes and optimizers
  - Open source (written in Python)
  - Minimally intrusive
    - solvers are kept as independent entities
    - leave participating codes unchanged
  - Generic
    - standardized interface function
    - models can easily be exchanged or added
  - Flexible
    - connect codes written in different languages
    - connect codes run on different platforms



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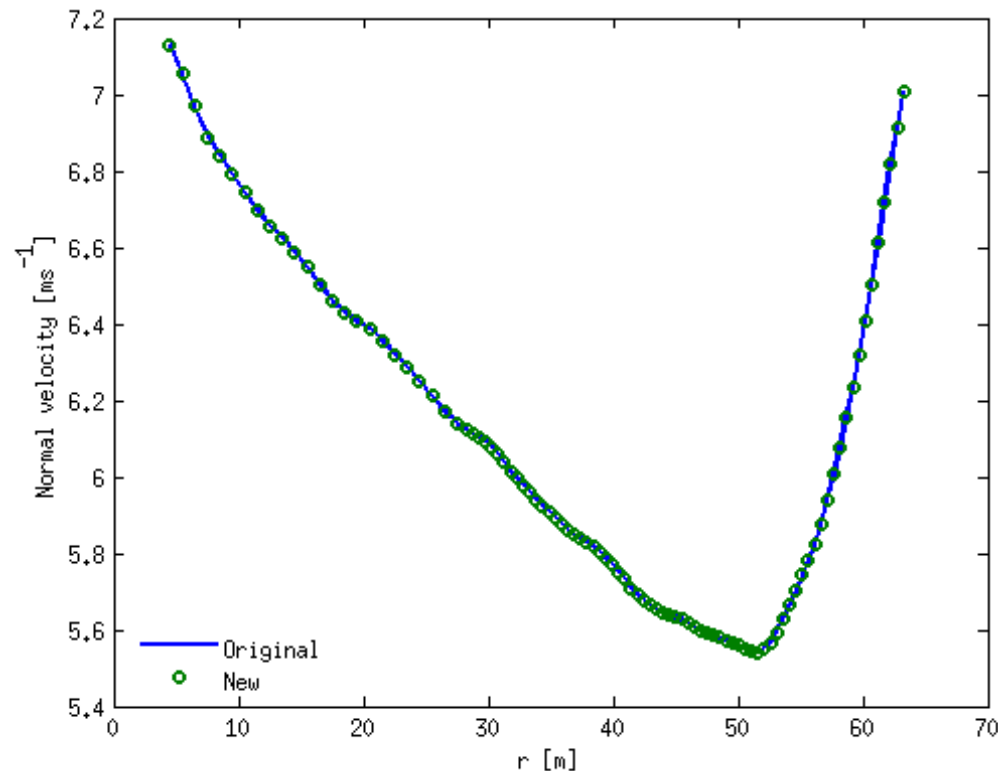


# Simulating the NREL 5MW wind turbine

- Wind speed:  $V_{\infty} = 8$  m/s
- Rotational speed  $\Omega = 0.964$  rad/s
- Forces prescribed according to results from a full rotor simulation
- Blade section coordinates and blade loading provided by external routine (HAWC2 emulator)

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# Conclusions

- The actuator line method has been included in the OpenMDAO framework
- The actuator line method has been modified to make it as general as HAWC2, i.e. can handle a multiple of different types of turbines.
- First test case shows good results