A modified \mathbf{k} - ε model applied to wind farms [1]

M. Paul van der Laan

Supervisors and contributers: Niels Sørensen, Pierre-Elouan Réthoré, Jakob Mann, Mark Kelly, Niels Troldborg, Kurt Hansen, Juan Pablo Murcia

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DTU Wind Energy Department of Wind Energy



Outline









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Wind turbine wakes in an off-shore wind farm



Figure : Horns Rev off-shore wind farm. Photographer: Christian Steiness

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Wind turbine wakes in an off-shore wind farm



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Wakes in CFD



• The rotor forces are modeled with an actuator disk.



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- The flow is resolved with EllipSys3D.



- The rotor forces are modeled with an actuator disk.
- The flow is resolved with EllipSys3D.
- The flow is driven by turbulence since $Re \sim 10^7$.





• (•) Field measurements of Nibe wind turbine (D=40 m).

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- (•) Field measurements of Nibe wind turbine (D=40 m).
 - Resolve large scale turbulence using (-) Large-Eddy Simulation (LES).



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 - Model all turbulence using Reynold-Averaged Navier-Stokes (RANS):
 - (-) standard $k \varepsilon$ model.



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- (-) standard k-ε model.
- (-) $k \varepsilon f_P$ model.

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Velocity deficit



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Streamwise Reynolds-stress



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The \mathbf{k} - ε - $\mathbf{f}_{\mathbf{P}}$ model

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	The k - ε	- f P model [3].	

$$\overline{u'_{i}u'_{j}} = \frac{2}{3}k\delta_{ij} - \nu_{T}\left(\frac{\partial U_{i}}{\partial x_{j}} + \frac{\partial U_{j}}{\partial x_{i}}\right)$$
(1)
$$\nu_{T} = C_{\mu}f_{P}\frac{k^{2}}{\varepsilon}$$
(2)

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- An isotropic eddy-viscosity model with a variable C_{μ} .
- *f_P* is derived from Reynolds-stress modelling and it is based on the work of Apsley and Leschziner [2].

The \mathbf{k} - ε - $\mathbf{f}_{\mathbf{P}}$ model.



• σ as the shear parameter $\sigma \equiv \frac{k}{\varepsilon} \sqrt{\left(\frac{\partial U_i}{\partial x_j}\right)^2}$ and $\tilde{\sigma}$ is the shear parameter in the log law region.

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• In the log law
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: $f_P = 1$.

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- In the log law $(\sigma = \tilde{\sigma})$: $f_P = 1$.
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- In the log law $(\sigma = \tilde{\sigma})$: $f_P = 1$.
- High velocity gradients ($\sigma > \tilde{\sigma}$): $f_P < 1 \Rightarrow$ less dissipative.
- C_R controls the behavior of f_P . From calibration with LES: $C_R = 4.5$.

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Wind Farms

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Test cases: two wind farms.





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Test cases: two wind farms.



• Wieringermeer: Dutch on-shore wind farm, 5×2.5 MW.



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Test cases: two wind farms.



- Wieringermeer: Dutch on-shore wind farm, 5×2.5 MW.
- Horns Rev: Danish off-shore wind farm, 80×2 MW.



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	Wieringermeer	wind farm:	layout.



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Wieringermeer wind farm: power deficit.



Wieringermeer wind farm: atmospheric stability.



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Wieringermeer wind farm: atmospheric stability.



• Stable atmospheric stability cannot be modelled by simply lowering the turbulence intensity!

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Wieringermeer wind farm: effect of wake rotation.



Wind turbine

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Wieringermeer wind farm: effect of wake rotation.



• Effect of wake rotation on power deficit is negligible.

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Wieringermeer wind farm: effect of wake rotation.



- Effect of wake rotation on power deficit is negligible.
- In contradiction with Wu and Porté-Agel [4], but they used a different AD force methods, for the wind farm simulations with and without wake rotation.

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Horns Rev wind farm: layout.



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Horns Rev wind farm: power deficit in row B.



Wind turbine

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Horns Rev wind farm: power deficit in row G.



• Why is the power deficit different for similar rows?

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- Why is the power deficit different for similar rows?
- Why are the RANS models overpredicting the power deficit?

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Answer \Rightarrow wind direction uncertainty of the measurements caused by:

• Spatial decorrelation of the reference wind direction measurement and power measurements.

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- Spatial decorrelation of the reference wind direction measurement and power measurements.
- Using wind turbine yaw sensors to determine as wind direction measurements.

- Why is the power deficit different for similar rows?
- Why are the RANS models overpredicting the power deficit?

Answer \Rightarrow wind direction uncertainty of the measurements caused by:

- Spatial decorrelation of the reference wind direction measurement and power measurements.
- Using wind turbine yaw sensors to determine as wind direction measurements.
- The change in wind direction due to large scale turbulence that is statistically not well represented within ten minute averages.

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Wind direction uncertainty in the Horns Rev wind farm.



$$\Delta \theta_i = \theta_{yaw,i} - \theta_{M2,i} \qquad (3)$$

Introduction The k-e-fp model Wind farms Conclusions and future work Including the wind direction uncertainty as a Gaussian average.

Simulate multiple wind directions on an interval $\pm 3\sigma$:



$$\mathsf{Power} = \sum_{i=1}^{N} \mathsf{Power}(\theta_i) \times \mathsf{probability}(\theta_i) \tag{4}$$

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 Horns Rev wind farm: power deficit in row B including wind direction uncertainty.
 Output
 Output



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 Horns Rev wind farm: power deficit in row G including wind direction uncertainty.
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 In terms of velocity deficit the k-ε-f_P model shows large a improvement compared to the standard k-ε model.

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- In terms of velocity deficit the k-ε-f_P model shows large a improvement compared to the standard k-ε model.
- The improvements are realized by introducing a variable C_{μ} that decreases the eddy-viscosity behind the wind turbine and delays the wake recovery.

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- In terms of velocity deficit the k-ε-f_P model shows large a improvement compared to the standard k-ε model.
- The improvements are realized by introducing a variable C_{μ} that decreases the eddy-viscosity behind the wind turbine and delays the wake recovery.
- The k-ε-f_P model does not improve the wake turbulence significantly because it is an isotropic turbulence model.

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Win	d farms [.]		

• The effect of wake rotation on the power deficit is negligible.

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• Stable atmospheric stability cannot be modelled by lowering the turbulence intensity.

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• Wind • •	d farms: The effect of wake rota Stable atmospheric stal the turbulence intensity	tion on the power bility cannot be mo	deficit is negligible. odelled by lowering

• The measured power deficit in wind farms have a high wind direction uncertainty.

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Wind	farms:		
•	The effect of wake rota Stable atmospheric stat	tion on the power bility cannot be m	deficit is negligible. odelled by lowering

- the turbulence intensity.
- The measured power deficit in wind farms have a high wind direction uncertainty.
- Including the measured wind direction uncertainty as Gaussian average of a range of simulated wind directions leads to a more fair comparison.

Conclusions
• Wind farms:
 The effect of wake rotation on the power deficit is negligible.

• Stable atmospheric stability cannot be modelled by lowering the turbulence intensity.

Conclusions and future work

- The measured power deficit in wind farms have a high wind direction uncertainty.
- Including the measured wind direction uncertainty as Gaussian average of a range of simulated wind directions leads to a more fair comparison.
- The k-ε-f_P model compares better with the measurements than the standard k-ε model, especially for closely spaced wind turbines.

Conclusions	
• Wind farms:	

The k-s-fp model

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 Stable atmospheric stability cannot be modelled by lowering the turbulence intensity.

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- The measured power deficit in wind farms have a high wind direction uncertainty.
- Including the measured wind direction uncertainty as Gaussian average of a range of simulated wind directions leads to a more fair comparison.
- The k-ε-f_P model compares better with the measurements than the standard k-ε model, especially for closely spaced wind turbines.
- Both RANS models calculate similar power deficits at the third/fourth wind turbine in a row. Hence, the standard k-ε model may not be a bad model choice if the anual energy production of large wind farms needs to be calculated.

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• Model the effects of stable atmospheric stability in RANS.

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- Model the effects of stable atmospheric stability in RANS.
- Further investigate measurements uncertainty in wind farms.

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